

Fleet Conversion to EV – Summary Report

Undertaken for Northumbrian Water Limited 26 August 2024 www.ennovigasolar.com

26 August 2024 240826 ESL - NWL EV study results.pptx 1

Background

- NWL's carbon reduction commitment is challenging and will ultimately require emissions from mobility to be addressed. The most commercially mature technology at the moment is electric vehicles (EVs).
- NWL leases its vehicle fleet (1,100 vehicles) from VLS, a company it owns jointly with Northern Powergrid. Vehicles are generally driven home by the drivers, not back-to-base each night. Relatively complex analysis is required to work out the effect of converting to EV.
- The conversion to EV must not adversely affect each driver's routine or limit them from undertaking their work.
- ESL's work is heavily analytical and routinely addresses very complex issues; ESL has the capability and experience to undertake a complex EV conversion study.
- Conversion to EV should be economically rational and may not be right for some or all vehicles – the case needs to be made to do anything at all.

Background (2)

- NWL also concerned about the effect on their electricity bills if the vehicles are charging on-site, so the analysis must work out where and when the vehicles would charge.
- Furthermore, an EV fleet would need chargers to be installed at specific sites, and more expensive chargers can charge faster than cheaper slow chargers. So NWL wishes to know where to install how many of what capacity charger.
- In a subsequent phase, NWL may wish to undertake a discounted cash flow analysis for each vehicle to determine whether it is cost-effective to replace that vehicle with an electric version. Some vehicles may not be economic to replace with EV at present but may become economic in future.
- NWL may also choose to replace certain vehicle specifications with other specifications, for instance if the technician doesn't need such a large carrying capacity, but a longer range might be better.

Data provided (1)

- NWL's IVMS operator (Inseego) provided ESL with 2-years worth of vehicle trips as CSV files. These contained some data, but it was curious that other data (e.g. odometer readings) were not included.
- ESL cleaned and processed the data. Some inefficiencies were found, for instance Inseego data did not provide the seconds on the timestamps so in some cases there were multiple journeys recorded at the same time, whereas in reality they were likely sub-minute journeys.
- NWL provided a spreadsheet with their fleet data but some of this clashed with similar data provided by Inseego.
- ESL generated its own table of EV replacement and matched each actual vehicle to the top five EV replacements where the best replacement was the one that would have resulted in the most EV miles.
- The dataset is far too large to manipulate on Excel. ESL created a PostgreSQL database and has been coding queries using additional resources to process the data.
- Assume the 2018 NWL GIS layer showing ownership boundaries is still valid.

Data provided (2)

- In April 2024, NWL's IVMS operator (Inseego) provided ESL with a further 1-year worth of vehicle trips as CSV files (covering 2023) on an identical basis as before.
- ESL cleaned and processed the data in the same way as before.
- NWL provided a new spreadsheet with their fleet data and again some of this was inconsistent with data provided by Inseego.
- ESL created its own list of NWL vehicles from the Inseego journey data, purchased DVLA data for these vehicles and treated the DVLA data as the master set.
- NWL provided an updated GIS layer showing ownership boundaries. ESL originally understood that this layer matched the Land Registry shapes registered to NWL but some shapes were found not to match those in the Land Registry. ESL assumed NWL's shapes were correct and eliminated those where the ownership shape was set to 200m squares.

Analysis assumptions – vehicles

- Exclude "vehicles" that are not relevant (e.g. generators) from the analysis.
- Assume that the last 3-years of actual vehicle movements is representative of future vehicle movements.
- **Assume that the drivers will only charge on NWL sites, and will only charge when the vehicle was otherwise parked (as per historical dataset).**
- Assume that the drivers will always use a slow charger, unless they must use a (more expensive) fast charger to reach their next destination.
- For now, assume no on-board electrical loads drawing power from the battery.
- For now, assume a constant kWh/mi consumption rate. Later this can be set to a temperature-dependent rate.
- For now, assume a linear battery charge rate. Later this can be replaced with a curve as battery charging slows once the battery state of charge (SoC) reaches 80%.

Analysis assumptions – geometry

- Plot all ~5mln journey end points on the GIS and overlay the NWL property boundary polygons.
- Exclude all NWL shapes that represent reservoirs.
- Draw a 10m buffer around all NWL property polygons.
- Select all vehicle journey end points that land within the buffered polygons and add the name of the NWL property to each journey.
- **Future work**: some of the NWL property polygons are quite large. Based on the distribution of the actual journey end points, these large sites should be split into multiple separate destinations and the entire analysis rerun accordingly.

Method – choose replacement vehicles

To choose which model of EV is the ideal replacement for each existing vehicle:

- Created a table of every EV replacement candidate together with its payload volume, payload weight, towing capacity, battery size, energy consumption and cost.
	- OEM datasheets provide inconsistent consumption figures. ESL recorded two separate consumption figures: a conservative one using the official OEM range * 0.75 / OEM battery capacity * 0.9, and the official OEM consumption rate converted to miles / kWh.
	- This analysis uses the conservative version that is more representative of "real world conditions".
- For each vehicle, choose a shortlist of EV candidates where the EV payload weight <= 1.5 x current payload weight, and EV payload volume >= current payload volume, and EV vehicle length <= 1.2 x current vehicle length.
- Run the full hindcast analysis for each fleet vehicle against each shortlisted candidate EV model and create a table recording that replacement EV's suitability score where score = count of successful EV miles driven / total miles driven.
- Post-process the results table to create a ranking of which five replacement EV models are most suitable for each vehicle.

Method – vehicle journeys

- For each vehicle, look up the replacement vehicle's battery size, assume it starts full, and then calculate how much charge is consumed for each journey.
- When a journey ends at a site that has a NWL site name attributed to it, assume this is a charge point.
- Work out how long the vehicle is stopped at the charge point.
- If the vehicle can reach its next destination using the charge remaining in the battery plus charge added by a slow charger during the time it is stopped, then use a slow charger.
- If it cannot reach the destination with the slow charge, then use a fast charger. Assume that the fast charger can supply the maximum charge rate for that vehicle.
	- NB: This results in the maximum range but also the highest capacity charger. **Future work**: rerun this accounting for charger cost and consider whether a smaller capacity fast charger is better value.
- Then work out how many journeys can be completed without running out of charge.
- **Future work**: use battery charge curves rather than assume linear charge rates this requires OEMs to share their charge curves (presently they don't).

Method – charging sites

- Based on the vehicle journey analysis, work out how many vehicles stop at each company site on a timeline.
- Group the results into half-hourly time slots that match the electricity market.
- Apportion the amount of electricity added to each vehicle to the appropriate time slot.
- Add up the amount of electricity used to charge EVs per site in HH time slots for the entire timeline.
- Simplify this to just 48 HH time slots to get an idea of when charging happens.
- A second iteration of this was done grouping the charge slots into 5-min rather than 30-min bins because using 30-min bins calculates a higher number of required chargers than is actually needed.
- **Future work**: check the maximum charging current needed and compare to each site's grid connection agreement.

EV charger types

AC

- 3.7 kW (1-phase, 16A)
- 7.4kW (1-phase, 32A)
- 11kW (3-phase, 16A)
- 22kW (3-phase, 32A)

DC

- 22.5kW
- 50kW
- All the way to 1MW

Cables

Tethered (in-built cable) Untethered (no cable)

Charger specification considerations

- ISO 15118
	- Standard allows car to talk to the charge point and vice-versa and to recognise the car (and allow charge) without RFID or other key fobs.
- Open Charge Point Protocol (OCPP 2.0)
	- A communication between an EV charging station and a central back-office system.
- Charge Point Management System
	- Software used to oversee all EV charging stations, collect usage statistics, allocate charges to vehicles / cost codes, track charger faults, etc.
- Dynamic Load Management
	- Functionality where the chargers dial back their current to not exceed DNO limits. Can be smart and use solar generation or battery when available.
- Charging hubs
	- Single large DC device distributes power to multiple dispensers meaning that capacity can be distributed as needed (e.g. 250kW to one vehicle and 20kW to another). For supply constrained sites may enable more charging.

Discussion on method

- This type of hindcast analysis is very rigorous because it is based on real vehicle journey data and it minimises the number of assumptions needed.
- The results are very strongly driven by two key boundary conditions:
	- Only charge on NWL sites (to not introduce price complexity);
	- Only allow charging during the time that the vehicle was anyway stopped (e.g. no dedicated charging time allowed).
	- To explore the effect the second condition has on the results, this study was run twice:
		- The first time, "% EV miles" was calculated based on whether each vehicle is technically capable of undertaking each journey (e.g. is the vehicle's range > distance to next charge stop). This resulted in a high EV suitability fraction with some 321 vehicles 100% suitable for immediate conversion.
		- The second time, "% EV miles" was calculated using each vehicle's actual range based on the calculated battery state of charge. As charging time was restricted, much fewer vehicles (e.g. only 10) were found to be 100% suitable for immediate conversion.
- These contrasting results highlight that suitable EVs are available today, and that the key to maximising, "% EV miles" likely requires taking battery state of charge into account during journey scheduling, and maximising charging opportunities.

Discussion on method (2)

- This analysis calculated the number of chargers needed per NWL "site". However some NWL "sites" are huge and a future iteration ought to break large NWL sites into sub-sites and calculate the number of chargers needed on that basis. This could result in a higher number of chargers.
- Some uncertainty exists on how scheduling and human effects will affect actual journeys:
	- Can NWL connect real-time battery state of charge to its job dispatching software to increase the number of successful EV miles?
	- How close to the mathematical optimum will drivers actually behave? Will they loiter longer at NWL sites to charge more due to 'range anxiety', and will this result in congestion at charge points?
- Some concerns exists about EV drivers:
	- not plugging in (for instance during short stops and especially during foul weather), and
	- occupying and thus blocking fast chargers when they only need a slow charger, and
	- excessively using much more costly public chargers for convenience.
- These concerns likely require practical experience to both gauge their frequency and to identify effective mitigations.

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Results

Charger count, all journeys, technical range (5-min bin)

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Charger count, 100% EV vehicles, technical EV range (5-min bin)

Charger count, 75% EV vehicles (actual EV range) (5-min bin)

Count of replacement EV models, entire fleet

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117 - Renault Trafic E-TECH LH30

92 - Mercedes-Benz eSprinter 420 Van L2

94 - Mercedes-Benz eSprinter 320 Van L3

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 $\mathbf{1}$

 $\mathbf{1}$

3 - Citroen e-Dispatch Panel Van M

21 - Ford E-Transit Van 350 GVM L3H2

17 - Fiat E-Ducato Van 40 L4H2

92 - Mercedes-Benz eSprinter 420 Van L2

100 - Mercedes-Benz eVito 66kWh Van L3

4 - Citroen e-Dispatch Panel Van XL

44 - Iveco eDaily 42C 4100WB H2 3B

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24 - Ford E-Transit Van 390 GVM L2H2

3 - Citroen e-Dispatch Panel Van M

34 - Iveco eDaily 35S 3520WB H2 1B

81 - Maxus eDeliver 9 L3H3 77kWh

 $\overline{1}$

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 $\mathbf{1}$

 $\bf{12}$ $\bf{11}$ ${\bf 10}$ 10

Vehicles ranked by total mileage

Potential EV mileage as % of each vehicle journeys

Vehicles ranked by total mileage

Potential EV mileage as % of each vehicle journeys

Historical vehicle dwell times

NWL models that can be converted to EV

The columns in these tables show how many of each current NWL fleet model vehicles can achieve various "% EV miles", where [Table 1] is calculated using the "technical range" method, and [Table 2] is calculated using the "actual range" method.

Count of replacement EVs by battery size, entire fleet

Historical mileage and trip length by dept, all journeys

1-Jan-2020 to 31-Dec-2023

sum of distance avg2_trip_dist avg2_trip_min

Historical mileage and trip length by level, all journeys

sum avg2_trip_dist avg2_trip_min

Historical mileage by vehicle model, all journeys

avg2_trip_dist avg2_trip_min \blacksquare sum

Journeys as % of vehicle range by dept, all journeys

Ratio of journey distance divided by maximum range

■a) <=10% ■b) 20% ■c) 30% ■d) 40% ■e) 50% ■f) 60% ■g) 70% ■h) 80% ■i) 90% ■j) 100%

Journeys as % of vehicle range by dept, all journeys (2)

Ratio of journey distance divided by maximum range

■a) <=10% ■b) 20% ■c) 30% ■d) 40% ■e) 50% ■f) 60% ■g) 70% ■h) 80% ■i) 90% ■i) 100% ■p) >100%

Journeys as % of vehicle range by dept, all journeys (3)

Ratio of journey distance divided by maximum range

■a) <=10% ■b) 20% ■c) 30% ■d) 40% ■e) 50% ■f) 60% ■g) 70% ■h) 80% ■i) 90% ■i) 100% ■p) >100%

Phasing of charging demand, all journeys

Sum of all sites hindcast 2021-2023

Thank you

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